Non Local Means

ISO Images¹

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$$u: \bar{D} \to \mathbb{R}^3$$
 – original colour image,
 $u_0: \bar{D} \to \mathbb{R}^3$ – noisy colour image,

$$u_0=u+\eta,$$

$$\eta$$
 – Gaussian noise.

We are given u_0 , the problem is to reconstruct u.

The Inverse Problem

- ► linear filtering
- wevelets theory
- ► variational mathods
- ► PDE-based methods
- ▶ stochastic modelling
- ▶ non local means approach

Non Local Means

Let $v = \{u_0(i) | i \in I = \mathbf{Z}^2 \cap D\}$ be a discrete noisy image

$$NL(v)(i) = \sum_{j \in I} w(N_i, N_j)v(j).$$

The weight $w(N_i, N_i)$ depends on the similarity of the intensity gray level or colour vectors of neighbourhoods N_i , N_i centred at pixels i and i

Algorithm for Non Local Means

Let $B_{i,F}$ be a window of size $F \times F$ centred at i

$$u(i) \leftarrow 0; Z \leftarrow 0;$$
 Buades et al. (2005)
for $j \in B_{i,F}$ do
 $u(i) \leftarrow u(i) + w(B_{i,r}, B_{j,r}) \cdot v(j);$
 $Z \leftarrow Z + w(B_{i,r}, B_{j,r});$
end for
 $u(i) \leftarrow \frac{u(i)}{Z};$
 $w(B_{i,r}, B_{j,r}) = \exp\left(-\frac{\max\left(\frac{\|B_{i,r} - B_{j,r}\|^2}{3(2r+1)} - 2\rho^2, 0\right)}{s^2}\right)$
Buades et al. (2011)

$$\frac{\partial u}{\partial t} = Au$$

$$u(t,x)=\mathbf{E}\left[u_0(X_t)\right]$$

Non Local Means

$$X_{0} = x,$$
Borkowski (2013)

$$H_{k} = \prod_{D} (X_{k-1} + h \cdot (\Phi_{0,1}, \Phi_{0,1}))$$

$$X_{k} = \begin{cases} H_{k}, & \text{if } \Theta, \\ X_{k-1}, & \text{elsewhere,} \end{cases} \qquad k = 1, 2, ..., \tau_{m},$$

 $\Pi_D(x)$ denotes a projection of x on the set D $\Phi_{0,1}$ is a random number generator from the normal distribution with mean 0 and standard deviation 1.

By Θ we mean the condition

$$||(G_{\delta} * u_0)(H_k) - (G_{\delta} * u_0)(X_{k-1})|| \le 0.8 \cdot \rho$$

where G_δ is 3×3 Gaussian mask and by au_m

$$\tau_m = \min\{k; k \ge m \text{ and } \Theta \text{ is true } m \text{ times}\}.$$

$$u(x) \approx \sum_{i=1}^{M} \frac{1}{M} u_0(X_{\tau_m(\omega_i)}(\omega_i)),$$

Experimental Results

```
1: u(i) \leftarrow 0; X(0) \leftarrow i;
 2: for m = 1 ... M do
     k \leftarrow 1:
        while k \le K do
           X(k) \leftarrow \Pi_D (X(k-1) + h \cdot (\Phi_{0,1}, \Phi_{0,1}));
 5:
           if |G_{\delta} * u_0(X(k)) - G_{\delta} * u_0(X(k-1))| \le 0.8 \cdot \rho then
 6:
               k \leftarrow k + 1:
 7:
           end if
 8:
        end while
 9:
        u(i) \leftarrow u(i) + \frac{1}{M} \cdot u_0(X(K));
10:
11: end for
```

$$u(x) = \frac{1}{Z} \sum_{i=1}^{M} w(B_{x,r}, B_{X_{\tau_m(\omega_i)}(\omega_i),r}) u_0(X_{\tau_m(\omega_i)}(\omega_i)).$$

Experimental Results

New Algorithm

Non Local Means

```
1: u(i) \leftarrow 0; X(0) \leftarrow i; Z \leftarrow 0;
 2: for m = 1 ... M do
 3: k \leftarrow 1:
        while k \le K do
            X(k) \leftarrow \Pi_D (X(k-1) + h \cdot (\Phi_{0,1}, \Phi_{0,1}));
 5:
            if |G_{\delta} * u_0(X(k)) - G_{\delta} * u_0(X(k-1))| < 0.8 \cdot \rho then
 6:
               k \leftarrow k + 1:
 7:
            end if
 8:
         end while
 9.
        u(i) \leftarrow u(i) + w\left(B_{i,r}, B_{X(K),r}\right) \cdot u_0(X(K));
10:
        Z \leftarrow Z + w(B_{i,r}, B_{X(K),r});
12: end for
13: u(i) \leftarrow \frac{u(i)}{7}:
```





Figure : Original test images: 512×512 a) Peppers b) Lenna

PSNR

| Image | Noise ρ | NL-means | Stoch. anis. diff. | New method |
|---------|--------------|----------|--------------------|------------|
| Peppers | 10 | 32.9404 | 32.3572 | 33.1289 |
| | 20 | 30.2984 | 30.6057 | 31.0984 |
| | 30 | 27.3031 | 29.2140 | 29.8178 |
| | 40 | 26.6428 | 28.1988 | 28.6991 |
| | 50 | 25.9941 | 27.2549 | 27.8611 |
| | 60 | 25.5353 | 26.5094 | 27.0802 |
| Lenna | 10 | 34.0127 | 33.0964 | 34.3550 |
| | 20 | 31.5780 | 31.1301 | 31.8386 |
| | 30 | 29.6376 | 29.6041 | 30.2871 |
| | 40 | 28.6433 | 28.5068 | 29.0773 |
| | 50 | 27.7377 | 27.5843 | 28.1308 |
| | 60 | 27.0094 | 26.7234 | 27.3205 |

SSIM

| Image | Noise ρ | NL-means | Stoch. anis. diff. | New method |
|---------|--------------|----------|--------------------|------------|
| Peppers | 10 | 0.9536 | 0.9470 | 0.9548 |
| | 20 | 0.9194 | 0.9146 | 0.9232 |
| | 30 | 0.8898 | 0.8866 | 0.8994 |
| | 40 | 0.8645 | 0.8645 | 0.8759 |
| | 50 | 0.8383 | 0.8447 | 0.8564 |
| | 60 | 0.8284 | 0.8229 | 0.8362 |
| Lenna | 10 | 0.9588 | 0.9467 | 0.9573 |
| | 20 | 0.9224 | 0.9115 | 0.9232 |
| | 30 | 0.8929 | 0.8790 | 0.8930 |
| | 40 | 0.8640 | 0.8528 | 0.8648 |
| | 50 | 0.8377 | 0.8289 | 0.8414 |
| | 60 | 0.8174 | 0.8050 | 0.8176 |

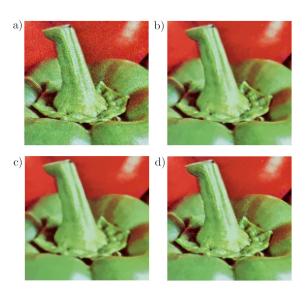


Figure : a) Noisy image $\rho=$ 10 b) New method c) Anisotropic diffusion d) NL-means

Experimental Results

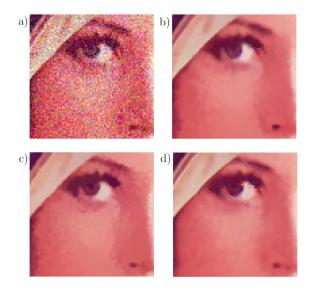


Figure : a) Noisy image $\rho=$ 30 b) New method c) Anisotropic diffusion d) NL-means

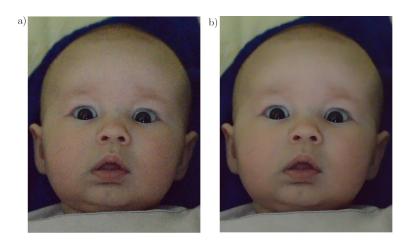


Figure : a) Input high ISO image b) Result of the reconstruction using new method

Conclusion

Applying the Feynman-Kac formula to express anisotropic diffusion in stochastic terms allows to adapt the idea from non local means, giving what is the best from these two classical approaches.